

# TDA2004R

## 10 + 10 W stereo amplifier for car radio

## Features

- Low distortion
- Low noise
- Protection against:
  - Output AC short circuit to ground
  - Overrating chip temperature
  - Load dump voltage surge
  - Fortuitous open ground
  - Very inductive loads

## Description

The TDA2004R is a class B dual audio power amplifier in Multiwatt11 package specifically designed for car radio applications.



Power booster amplifiers can be easily designed using this device that provides a high current capability (up to 3.5 A) and can drive very low impedance loads (down to 1.6  $\Omega$ ).

The TDA2004R allows very compact applications because few external components are required and it doesn't need electrical insulation between the package and the heatsink.

## Table 1.Device summary

Order code	Package	Packing	
TDA2004R	Multiwatt11	Tube	

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### **Pins description** 1



#### Figure 1. Pins connection diagram (top view)



# 2 Electrical specifications

## 2.1 Absolute maximum ratings

Table 2.	Absolute maximum ratings
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Symbol	Parameter	Value	Unit	
	Operating supply voltage	18		
VS	DC supply voltage	28	V	
	Peak supply voltage (50 ms)	40		
lo <sup>(1)</sup>	Output peak current (non repetitive t = 0.1 ms)	4.5	А	
10( )	Output peak current (repetitive f ≥10 Hz)	3.5	A	
P <sub>tot</sub> Power dissipation at T <sub>case</sub> = 60 °C		30	W	
T <sub>stg</sub> , T <sub>j</sub>	Storage and junction temperature	-40 to 150	°C	

1. The max. output current is internally limited.

## 2.2 Thermal data

### Table 3. Thermal data

Symbol	Parameter		Value	Unit
R <sub>th-j-case</sub>	R <sub>th-j-case</sub> Thermal resistance junction-to-case		3	°C/W

## 2.3 Electrical characteristics

Refer to the stereo application circuit  $T_{amb}$  = 25 °C;  $G_v$  = 50 dB;  $R_{th(heatsink)}$  = 4 °C/W unless otherwise specified

 Table 4.
 Electrical characteristics

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V <sub>S</sub>	Supply voltage		8		18	V
Vo	Quiescent offset voltage	V <sub>S</sub> = 14.4 V V <sub>S</sub> = 13.2 V	6.6 6	7.2 6.6	7.8 7.2	V V
۱ <sub>d</sub>	Total quiescent drain current	V <sub>S</sub> = 14.4 V V <sub>S</sub> = 13.2 V	-	65 62	120 120	mA mA
Po	Output power (each channel)	$      f = 1 \text{ kHz}; \text{ THD} = 10 \% \\ V_S = 14.4 \text{ V}; \text{ R}_L = 4 \Omega \\ V_S = 14.4 \text{ V}; \text{ R}_L = 3.2 \Omega \\ V_S = 14.4 \text{ V}; \text{ R}_L = 2 \Omega \\ V_S = 14.4 \text{ V}; \text{ R}_L = 1.6 \Omega $	6 7 9 10	6.5 8 10 11	-	W



Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
Po	Output power (each channel)	f = 1  kHz; THD = 10 % $V_{S} = 13.2 \text{ V; } R_{L} = 3.2 \Omega$ $V_{S} = 13.2 \text{ V; } R_{L} = 1.6 \Omega$ $V_{S} = 16 \text{ V; } R_{L} = 2 \Omega$	6 9	6.5 10 <sup>(1)</sup> 12	-	w
		f = 1 kHz; V <sub>S</sub> = 14.4 V; R <sub>L</sub> = 4 Ω; P <sub>o</sub> = 50 mW to 4 W;	-	0.2	1	%
TUD		$f = 1 \text{ kHz}; V_S = 14.4 \text{ V};$ R <sub>L</sub> = 2 Ω; P <sub>0</sub> = 50 mW to 6 W;	-	0.3	1	%
THD	Total harmonic distortion	f = 1 kHz; V <sub>S</sub> = 13.2 V; R <sub>L</sub> = 3.2 Ω; P <sub>o</sub> = 50 mW to 3W;	-	0.2	1	%
		$\label{eq:result} \begin{split} f &= 1 \text{KHz}; \ \text{V}_{\text{S}} = 13.2 \text{V}; \\ \text{R}_{\text{L}} &= 1.6 \Omega; \ \text{P}_{\text{o}} = 40 \text{mW} \ \text{to} \ 6 \text{W}; \end{split}$	-	0.3	1	%
ст	Cross talk		50 40	60 45	-	mW mW
Vi	Input saturation voltage	-	300		-	mW
R <sub>i</sub>	Input resistance	f = 1 kHz	70	200	-	kΩ
fL	Low frequency roll off (-3 dB)	$R_{L} = 4 \Omega$ $R_{L} = 2 \Omega$ $R_{L} = 3.2 \Omega$ $R_{L} = 1.6 \Omega$	-	-	35 50 40 55	Hz
f <sub>H</sub>	High frequency roll off (-3 dB)	$R_L = 1.6 \Omega$ to $4 \Omega$	15	-	-	kHz
	Open loop voltage gain	f = 1 kHz	-	90	-	
G <sub>v</sub>	Closed loop voltage gain	f = 1 kHz	48	50	51	dB
$\Delta G_v$	Closed loop gain matching	-	-	0.5	-	dB
e <sub>N</sub>	Total input noise voltage	$R_{g} = 10 \ k\Omega^{(2)}$	-	1.5	5	μV
SVR	Supply voltage rejection	$V_{ripple} = 0.5$ Vrms; $f_{ripple} = 100$ Hz; R <sub>g</sub> = 10 kΩ; $C_3 = 10$ μF	35	45	-	dB
	Efficiency	$f = 1 \text{ kHz; } V_{\text{S}} = 14.4 \text{ V;}$ $R_{\text{L}} = 4 \Omega; P_{\text{o}} = 6.5 \text{ W;}$ $R_{\text{L}} = 2\Omega; P_{\text{o}} = 10 \text{ W;}$	-	70 60	-	%
η	Enciency	f = 1 kHz; V <sub>S</sub> = 13.2 V; R <sub>L</sub> = 3.2 Ω; P <sub>o</sub> = 6.5 W; R <sub>L</sub> = 1.6 Ω; P <sub>o</sub> = 10 W;	-	70 60	-	%
Т <sub>Ј</sub>	Thermal shutdown junction temperature	-	-	145	-	°C

Table 4.	Electrical	characteristics	(continued)
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1. 9.3 W without bootstrap.

2. Bandwidth filter: 22 Hz to 22 kHz.



## 2.4 Test and application circuit





Figure 3. Printed circuit board and components layout of the figure 2





#### 2.5 **Electrical characteristics curves**

Figure 4. Quiescent output voltage vs. supply voltage







 $R_L = 2 \text{ and } 4 \Omega$ 



Output power vs. supply voltage, Figure 8.  $R_L = 1.6$  and  $3.2\Omega$ 

f = 1 kHz

 $G_{V} = 50 \text{ dB}$ d = 10 %

R<sub>L</sub> = 1.6 Ω

R<sub>L</sub> = 3.2 Ω

P<sub>0</sub> (W)

15

12

9

6

3

0

8

10

12

14

16

 $V_{S}(V)$ 









#### Figure 10. Distortion vs. frequency, $R_L = 1.6$ Figure 11. Supply voltage rejection vs. C3 and 3.2 $\Omega$

Figure 12. Supply voltage rejection vs. frequency

Supply voltage rejection vs. C2 and Figure 13. **C3**, **G**<sub>V</sub> = **390/1**Ω



Figure 14. Supply voltage rejection vs. C2 and Figure 15. Gain vs. input sensitivity **C3**, **G**<sub>V</sub> = 1000/10Ω



Gv

100

V<sub>i</sub> (mV)

500

200

50

20

V<sub>S</sub> = 14.4 f = 1 kHz 14.4 V

 $\mathsf{R}_\mathsf{L} = 4 \ \Omega$ 

300

100

10 12

 $P_{o}(W)$ 



2 4 6 8

P<sub>o</sub> (W)

Figure 18. Maximum allowable power dissipation vs. ambient temperature

4 8 12 16 20 24





# 3 Application suggestion

The recommended values of the components are those shown on application circuit of *Figure 2*. Different values can be used; the following table can help the designer.

Component	Recommended value	Purpose	Larger than	Smaller than r
R1	120 kΩ	Optimization of the output signal symmetry	Smaller P <sub>omax</sub>	Smaller P <sub>omax</sub>
R2, R4	1 kΩ	Closed loop gain setting	Increase of gain	Decrease of gain
R3, R5	3.3 Ω	(1)	Decrease of gain	Increase of gain
R6, R7	1 Ω	Frequency stability	Danger of oscillation at high frequency with inductive load	
C1, C2	2.2 μF	Input DC decoupling	High turn-on delay	High turn-on pop, higher low frequency cutoff. Increase of noise
СЗ	10 µF	Ripple rejection	Increase of SVR, Increase of the switch-on time	Degradation of SVR
C4, C6	100 μF	Bootstrapping	-	Increase of distortion at low frequency
C5, C7	100 μF	Feedback input DC decoupling	-	-
C8, C9	0.1 μF	Frequency stability	-	Danger of oscillation
C10, C11	1000 to 2200 μF	Output DC decoupling	-	Higher low-frequency cut-off

 Table 5.
 Recommended values of the component of the application circuit

1. The closed loop gain must be higher than 26 dB.

## 3.1 Built-in protection systems

## 3.1.1 Load dump voltage surge

The TDA2004R has a circuit which enables it to withstand voltage pulse train, on Pin 9, of the type shown in *Figure 20*. If the supply voltage peaks to more than 40 V, then an LC filter must be inserted between the supply and pin 9, in order to assure that the pulses at pin 9 will be held within the limits shown.

A suggested LC network is shown in *Figure 19*. With this network, a train of pulses with amplitude up to 120 V and width of 2 ms can be applied at point A. This type of protection is ON when the supply voltage (pulse or DC) exceeds 18 V. For this reason the maximum operating supply voltage is 18 V.







### Figure 20. Voltage gain bridge configuration



## 3.1.2 Short circuit (AC condition)

The TDA2004R can withstand a permanent short-circuit from the output to ground caused by a wrong connection during normal working.

### 3.1.3 Polarity inversion

High current (up to 10 A) can be handled by the device with no damage for a longer period than the blow-out time of a quick 2 A fuse (normally connected in series with the supply). This feature is added to avoid destruction, if during fitting to the car, a mistake on the connection of the supply is made.

### 3.1.4 Open ground

When the ratio is in the ON condition and the ground is accidentally opened, a standard audio amplifier will be damaged. On the TDA2004R protection diodes are included to avoid any damage.

### 3.1.5 Inductive load

A protection diode is provided to allow use of the TDA2004R with inductive loads.

### 3.1.6 DC voltage

The maximum operating DC voltage for the TDA2004R is 18 V. However the device can withstand a DC voltage up to 28 V with no damage. This could occur during winter if two batteries are series connected to crank the engine.



## 3.1.7 Thermal shut-down

The presence of a thermal limiting circuit offers the following advantages:

- 1. an overload on the output (even if it is permanent), or an excessive ambient temperature can be easily withstood.
- 2. the heatsink can have a smaller factor of safety compared with that of a conventional circuit. There is no device damage in the case of excessive junction temperature: all that happens is that  $P_o$  (and therefore  $P_{tot}$ ) and  $I_d$  are reduced.

The maximum allowable power dissipation depends upon the size of the external heatsink (i.e. its thermal resistance); *Figure 18* shows the power dissipation as a function of ambient temperature for different thermal resistance.



## 4 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: <u>www.st.com</u>.

 $ECOPACK^{
end{tabular}{R}}$  is an ST trademark.







# 5 Revision history

### Table 6.Document revision history

Date	Revision	Changes
18-Jun-2010	1	Initial release.



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